

PV SINGLE PHASE GRID CONNECTED CONVERTER USING FUZZY PID CONTROLLER

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ABSTRACT:

This paper proposes the Single phase multy stage grid interfaced Photo Voltaic System. The primary stage is DC-DC Booster stage which is governed by a MPPT system. Output voltage of Booster stage is controlled by Incremental conductance algorithm .Depending upon the solar Irradiation and temperature the output voltage of PV panel is varied. By MPPT the maximum power is drawn from the PV system and fed to Inverter stage. This stage controls the power flow to the grid. The proposed control will reduce the voltage ripple in DC link voltage. The conversion efficiency of Inverter will decrease due to ripples in DC link voltage ,because it it will cause an excessive stress on the IGBTs or MOSFETs. This also results harmonics in the grid current. This paper describes an efficient and reliable control technique , Fuzzy Proportional Integral Differential (FPID) for stabilizing the DC- link voltage. PV Array output is varied with variations in solar irradiation, temperature and shadow that means Photo Voltaic system is nonlinear. The change of plant parameters will not affect the proposed control technique. In this proposed scheme, power flow and THD levels are analyzed at different DC-link voltage. This study describes that this control technique have a capability to maintain a same grid current THD at transient and steady state conditions. Comparing to conventional PID control the % THD is small. Minimum settling time and fast DC-link voltage stabilization are also shown in this paper by this control technique. Finally the proposed system offers an excellent dynamic performance for reducing the DC-link voltage ripples and stabilization that is verified in MATLAB simulink tool

KEYWORDS: Fuzzy Propotional Integral Control; Maximum power point tracking

I. INTRODUCTION:

The relevance of renewable energy resources (like solar, wind etc.) as sources of electric power has been increased over the years because of the increasing demand of electricity, limited availability of conventional energy resources, and as a potential alternate to tackle global warming. The energy needs in the world is increasing day by day. The average increase is about 2% per day. To use only fossil fuel to meet this energy demand will reduce its short life time. The usage of fossil fuels will affect the environment. This situation will lead to alternate energy sources. Solar, Wind, Tidal and Geothermal are the renewable energy sources. In this, the wind and solar energy sources have the largest share in these resources. All over the world, wind and solar energy utilization is respectively 42% and 32% in alternative energy sources. The photovoltaic systems are preferred thanks to the absence of mechanical parts, directly electric energy generating, easy to use, low noise release and it is able to apply at every point in the world. Many types of solar energy conversion systems are used in the world. One of them is called concentrated solar power plants which are used to generate electricity from sun, and that power plants uses steam power at the same time. Another system is known as PV panels and it is extensively used. The PV panels are composed of a combination of chemical P and N materials. PV panels can directly convert the solar energy into electricity. In the distributed generation applications, PV system The formatter will need to create these components, incorporating the applicable criteria that follow. operates in two modes, namely, standalone mode and grid connected mode. In grid connected mode, the operation strategy of PV system is to extract maximum available power from the PV array and feed it to the grid. A typical Grid connected PV system has more than one stage of power conversion. The first stage consists of dc-dc converter to boost the voltage level such that it can extract maximum power from the PV array and the second stage

consists of dc-ac converter which supplies the extracted power from the PV array to ac grid. Nevertheless, there are many factors which affect the efficiency of PV panels such as air temperature, solar radiation and shadowing. In the day time these parameters constantly change. Accordingly, PV panel output power is changed by parameters. Different methods and techniques are used to eliminate this situation. The Maximum Power Point Tracking is one of the methods. The MPPT will sense the PV voltage and current and according to those values it will generate gate pulses for Boost chopper. For grid connected converters, efficient dc link voltage control is very important to reduce the voltage fluctuations in the dc-link. The DC-AC converter stage will supply ac power to the grid. For controlling the output voltage the gate pulses for the converter is generated by using conventional PID controller. But for nonlinear system, Fuzzy PID control is more effective. When FPID control is used the percentage THD will be comparatively reduced.

Power generated by PV system is effectively fed to grid by stabilizing the DC link voltage. The dc link voltage (1) stabilization is proposed without sensing the dc link voltage but by sensing PV voltage and current. Here the duty cycle of Boost chopper is controlled according to MPPT algorithm. The losses in converter stage is compensated by ANN in this paper. The DC-AC converter stage is controlled by PR controller. The V I characteristics of PV cell is nonlinear .It depends on the solar insulation and temperature. So the system needs efficient Maximum Power Point Tracking. Ripple Correlation Control (RCC) (2) yields fast and parameter insensitive is suitable for single phase single stage PV system. In Distributed Generations there are AC and DC sources and it forms DC sub grid and AC sub grid. The interface between these two (3) is Dual -Active-Bridge (DAB) and inverter Here DAB maintain the DC link voltage and inverter controls the power output by using feed forward loop which can improve system performance. The Predictive voltage control based on Energy- Balance (4) is applied for DC link voltage stabilization and it reduces output ripple. The DC-link voltage is not simply the sum of constant value and second order ripple. The inductance of the AC filter influences the amplitude of the DC-link voltage ripple. In this paper, reactive power is assumed to be zero that is grid current is in phase with voltage. When DAB converter (5) is used as first stage of dual stage PV grid inter phase system, the phase angle between the two voltages will decide the power that is transferred to grid. This angle is determined by sensing PV voltage DC-link voltage. The LCL filter at the input of (6) boost converter will reduce the inductance of Boost converter , which will reduce the cost

of converter. The author in (7) shows that the fuzzy PI MPPT is more effective and accurate than the Constant Voltage Controlled MPPT. In a 3 phase grid connected PV system the 3 phase VSC can also act as Active Power Filter in addition to stabilizing the DC-link voltage (8) without any additional hardware. MPPT using Fuzzy logic controller is simple and robust (9).This method can handle nonlinearity and it does not require the knowledge of exact model. The PV system is non linear. Conventional PID (10) controllers are not suitable for non linear system. In (4) Proportional Integral based Maximum Power Point, tracking control algorithm is proposed. This control enhances the generated power from PV system. The proposed system offers a PV V&I sensed Incremental conductance + Integral MPPT that controls the duty ratio of Boost chopper. An effective Fuzzy PID control is used in inverter stage to stabilize the DC-Link voltage.

II. PV MODULE:

PV Cell is a PN junction which converts solar irradiation directly to Electricity. Fig(2) shows the equivalent circuit. The PV cell current is I_{ph} and series and shunt resistances are R_{sh} and R_s respectively. Normally the series resistance is small hence for simplifying the analysis it may neglect. But the value of shunt resistance is large. When PV cells are connected in series resulting arrangement is called PV module. For getting large voltage these modules are connected in series or parallel. The resultant arrangement is called PV array. PV arrays are used in Solar power stations..

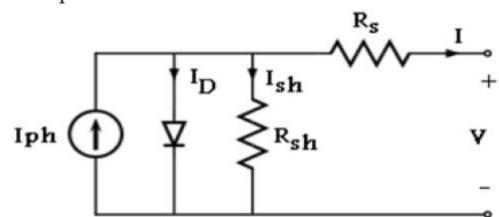


Fig.1, Equivalent Circuit of PV Cell

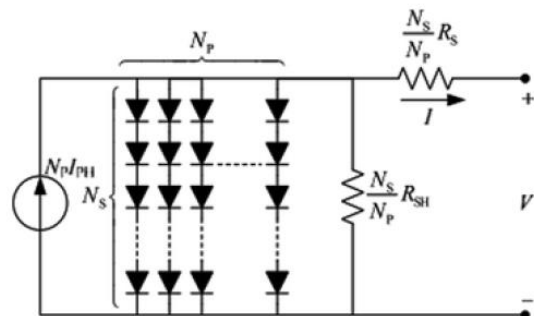


Fig 2. Equivalent Circuit of PV Array

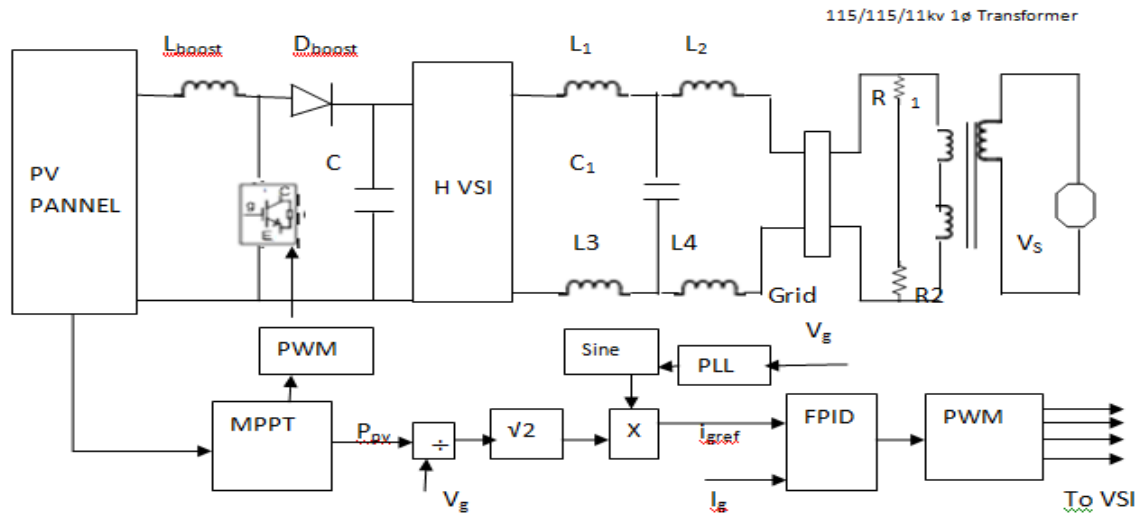


Fig.3. PV Grid Connected System

III POWER SYSTEM MODEL:

Figure 4.1 shows the proposed PV Grid connected system. This is a two stage PV system. First stage is a DC to DC Boost chopper stage. The function of DC-DC converter is to execute the MPPT algorithm by controlling its input terminal voltage by sensing the PV voltage and PV current. The MPPT algorithm used in this proposed system is Incremental conductance + integral regulator. This MPPT algorithm is simple and it automatically control the duty cycle. This sense the PV voltage and PV current and generate the gate pulses for the Boost chopper. For transferring maximum power to the grid it is required to stabilize the voltage. The un stabilized DC link voltage will cause large harmonic distortion in grid current and low power transfer from PV system to grid. The higher voltage at DC-link will cause stress in the power semiconductor switches used in Inverter stage. In the proposed system the DC link voltage is stabilized by a fuzzy PID controller in load current control loop. The second stage is inverter stage. This stage convert the DC voltage to AC voltage that is fed to the grid. The out put current of the H Bridge inverter contains the ripple. To reduce the ripple and thus to minimize the THD within IEEE standard LCL filter is used in out put circuit. In addition to this filter, since the PV system is a non linear, FPID, fuzzy Proportional Integral Derivative Controller is used in outer current control loop. This reduces the oscillation in DC-link voltage at transient and steady state conditions. It also helps to reduce the THD to considerable limit and reduces the settling time comparing to conventional PID and PR controller.

A. BOOSTER STAGE

Boost chopper is basically DC -DC converter its output voltage
 $V_o = V_s / (1-D)$, here D is duty ratio.

The gain of boost chopper is

$$G_{boost} = \frac{V_{out}}{V_{in}} = \frac{V_{dc}}{V_{pv}}$$

$$\text{That is } = \frac{1}{(1-D)}$$

$$\text{Maximum Switching Current } \Delta I = \frac{D \times V_{pv}}{F_{sw} \times L_{boost}}$$

If L is not known

$$\text{then } \Delta I = (0.2 \text{ to } 0.4) \times I_{out(max)} \times \frac{V_{out}}{V_{in}}$$

$$\text{So } L = \frac{V_{in} \times (V_{out} - V_{in})}{\Delta I \times F_{sw} \times V_{out}}$$

$$\text{Duty cycle } D = 1 - \frac{V_{in}}{V_{out}}$$

$$\text{Output capacitor } C_{out} = \frac{I_{out(max)} \times D}{F_{sw} \times \Delta V_{out}}$$

$$V_{out} = \frac{I_{out(max)}}{(1-D)} + \frac{\Delta I}{2}$$

B. INVERTER STAGE:

This stage convert the input Dc voltage to AC voltage at desired frequency and fed to the grid. For filtering the the switching frequency harmonics present in the output current LCL filters are used.

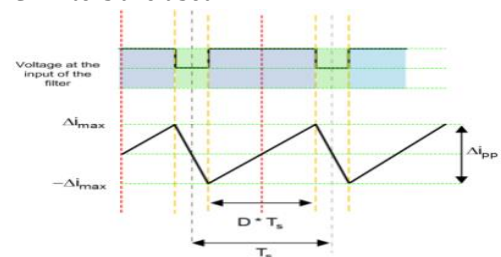


Fig 4. Voltage and Current wave form
 The voltage across the inductor is given by:

$$V = L \times \frac{di}{dt}$$

For H Bridge inverter $V = V_{bus} - V_o$

$$\text{So } V_{bus} - V_o = L \times \frac{di}{dt} = Li \times \frac{\Delta I_{pp}}{D \times Ts}$$

$$\Delta I_{pp} = \frac{(V_{bus} - V_o) \times D \times Ts}{Li}$$

Assume modulation index be m_a the Duty cycle is given as

$$D = m_a \times \text{sine}(\omega t)$$

$$V_o = V_{DC} \times D$$

Therefore,

$$\Delta I_{pp} = \frac{V_{bus} \times Ts \times m_a \times \text{sine}(\omega t) \times (1 - \text{sine}(\omega t))}{Li}$$

Differentiating the above equation and equating to zero we get,

$$\text{sine}(\omega t) = \frac{1}{2m_a}$$

$$\Delta I_{pp \text{ max}} = \frac{V_{bus} \times Ts}{4 \times Li}$$

$$Li = \frac{V_{bus}}{4 \times Fs \times \Delta I_{pp \text{ max}}}$$

IV. SIMULATION RESULTS:

Figure shows the proposed model of grid connected PV system. Here shows a grid with voltage of 200V and a 11KV/115-115 transformer that is connected to the grid. A 2.5 Kw PV array is connected to the grid through a DC-DC Boost chopper and single phase H bridge voltage source inverter. Maximum power point tracking (MPPT)

implemented in the boost chopper by means of incremental conductance +Integral Regulator technique.

PV array delivering a maximum of 2500 W at 1000 W/m² sun irradiance. A 20Khz DC-DC boost converter increasing voltage from PV natural voltage to maximum of 550V. switching frequency of H bridge inverter is 20KHz. The current control loop used Fuzzy PID controller because the PV system is non linear

A. FUZZY PID CONTROLLER

Proposed Fuzzy logic controller is help to achieve reasonable steady state error, settling time and reduced ripple in VSC output current. This is achieved because it does not sensitive to the plant parameter .The proposed system is used the Mamdani model and triangular membership functions. FPI have two inputs error and change of error (E & CE). It has one out put. In the proposed system reference current I_{ref} is compared with I_{grid} . Here reference current depends on PV Power and Grid voltage. The figure 6 shows the fuzzy rule base for the proposed system.

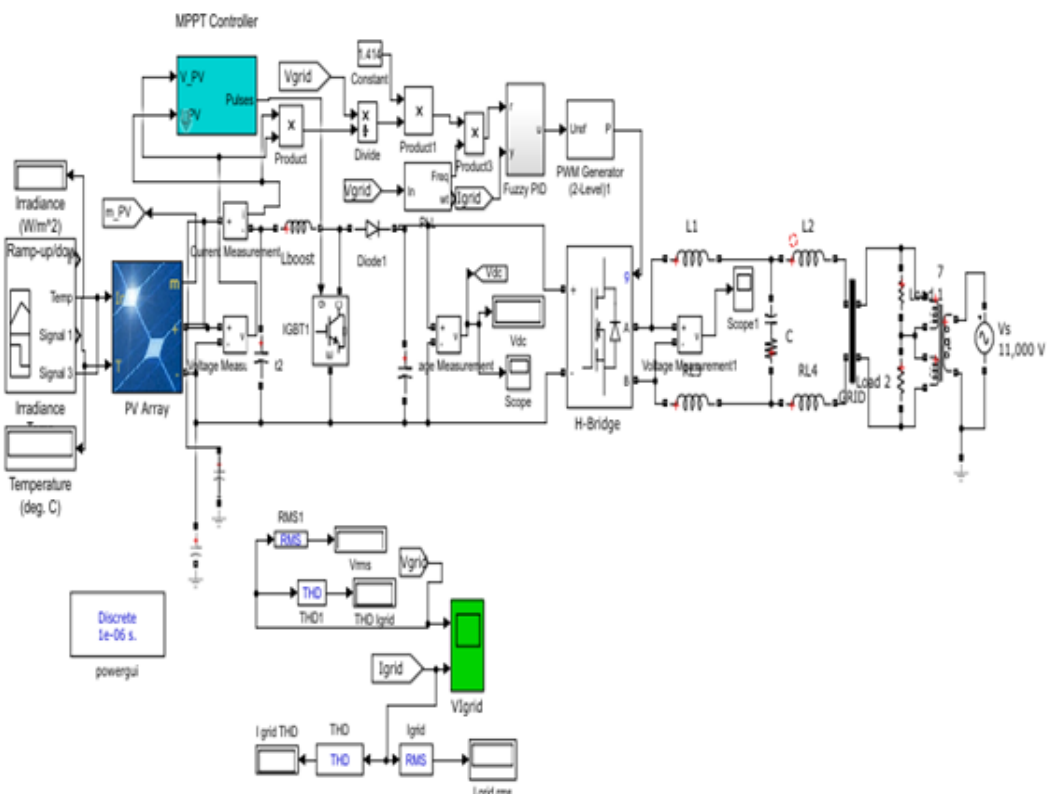


Fig. 5 Simulink Model of PV Grid Inter Phase System

CE E	NL	NS	Z	PS	PL
NL	NVL	NL	NM	NS	Z
NS	NL	NM	NS	Z	PS
Z	NM	NS	Z	PS	PM
PS	NS	Z	PS	PM	PL
PL	Z	PS	PM	PL	PVL

Fig.6 Fuzzy Rule

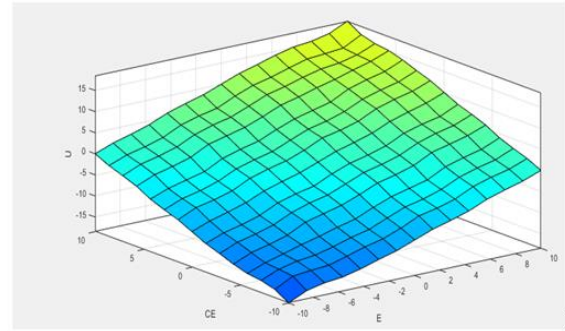


Fig.8 Rule Surface View

Here
 NS is Negative Small,
 NL is Negative Large,
 NM is Negative Medium,
 NVL is Negative Very Large,
 Z is Zero,
 PS is Positive Small,
 PM is Positive Medium,
 PL Positive Large and
 PVL is Positive Very Large

Defuzzification method used in simulation is centroid method. The proposed system has two inputs. One is Error (E) and the other one is Change of Error (CE).

$$E = e(k)$$

$$e(k) = I_{ref} - I_{grid}$$

$$I_{ref} = (P_{pv}) / V_{grid} \frac{P_{pv}}{I_{grid}}$$

$$CE = e(k) - e(k-1)$$

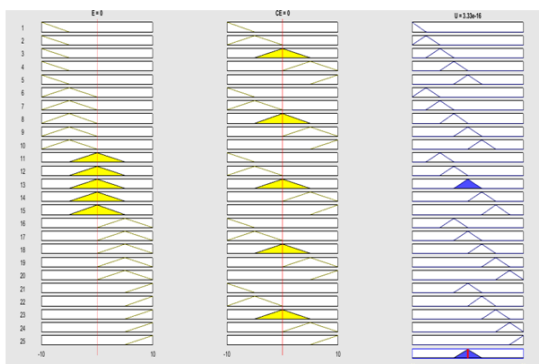


Fig.7 Fuzzy Rule for Proposed Control

B. STEADY STATE ANALYSIS:

MATLAB simulink 2017 is used for the simulation of the proposed system. Neo Solar Power 7E00-6A 250-B PV Array is used. The VI characteristics and Power Vs Voltage characteristics of the array are shown in figure.9

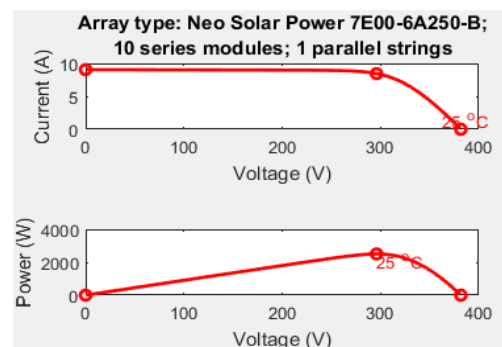


Fig.9 Characteristics of Neo Solar Power

Steady state results of the proposed system are shown in the following figures. Figure 11 shows the DC output voltage of the PV array. The PV voltage becomes steady after some seconds due to the characteristics of the PV panel. PV modules are connected in string, so the open circuit voltage at solar irradiation of 1000W/m² is 380 V at 25°C. The DC link voltage is varied from 300V onwards. The results show that the maximum power is transferred at minimum THD, which is below IEEE standards, at 350V. In the proposed system, DC link voltage fluctuations are minimized. This helps to reduce the stress on the VSI components.

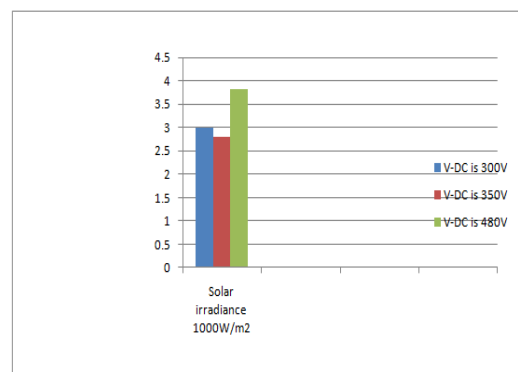


Fig.10 Percentage Grid Current at Different DC-Link Voltage,

Figure 10 shows the variation of % THD in grid current at different DC-Link voltage. Simulation results shows that % THD is comparatively small at 350 V DC-link voltage.

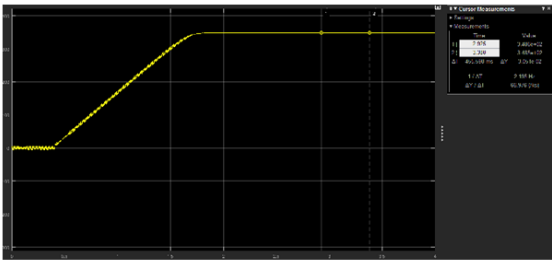


Fig 11. PV Output Voltage

Figure 12 shows the DC –Link voltage wave form at 1000W/m² irradiance and 25^o C. Figure 13 shows the H Bridge Voltage Source Inverter output voltage. The results shows that system takes about 5 seconds to reach the steady state value. This is due to the characteristics of the PV Array used in simulation that is shown in figure 9.

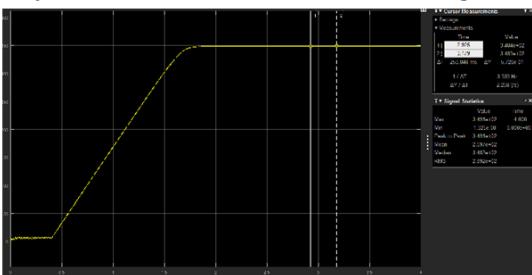


Fig.12. DC-Link Voltage

Steady state grid voltage and grid current wave forms are shown in figure 13. The voltage THD is very small and current THD is 0.028 at 1000 W/m² irradiance. Figure 13 shows the comparison of Proposed system with uncompensated conventional PR control based system and loss compensated conventional PR system. Comparing to these two systems the proposed system introduces small THD in the grid current.

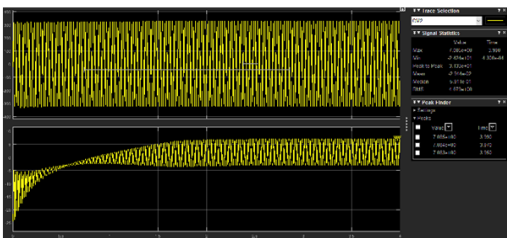


Fig 13. Grid Voltage and Current

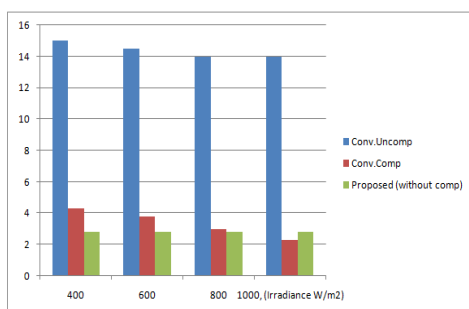


Fig 14 % THD at different solar irradiance

C. TRANSIENT ANALYSIS:

For transient analysis the solar irradiance is varied at 2.5 seconds keeping temperature as 25^o C. (Figure 15) . Figure 16 shows the variation on PV Voltage. Figure 17 shows the transient result of DC-Link voltage. Here, in the proposed system the settling time is 0.1 seconds.

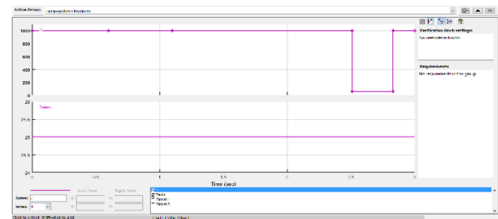


Fig.15 Solar Irradiance and Temperature

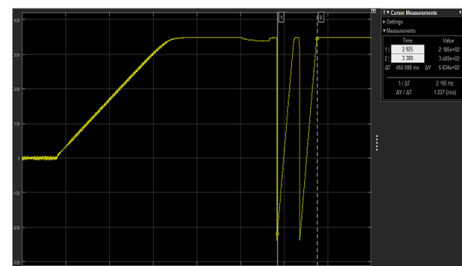


Fig 16 PV Voltage

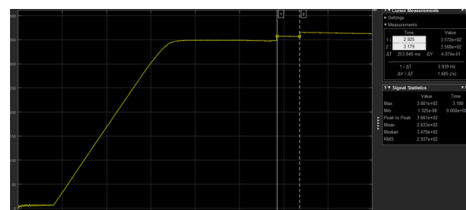


Fig 17 DC- Link Voltage

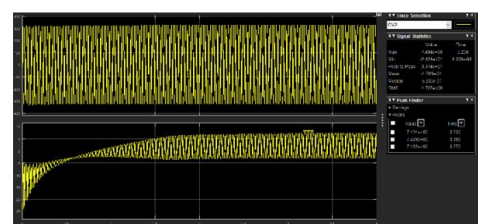


Fig 18 Grid Voltage and Current

V. CONCLUSION:

This study proposes an efficient control technique for stabilizing DC –Link voltage of a Grid connected single phase two stage converter. In this system the DC-link voltage is stabilized by introducing Fuzzy PID control. Comparing to conventional PID and PR control this Fuzzy Proportional Integral Differential System is most suitable for nonlinear system, like this PV grid connected system. This study proposed an enhanced power transmission from PV system to the grid. The total harmonic distortion is reduced under steady state analysis and transient analysis. The fuzzy logic system does not sensitive to plant parameter variation. So the proposed system offers same reduced THD level for grid current at different solar irradiance and temperature. Under transient conditions

the settling time reduced comparing to conventional systems. The proposed system is not account the converters loss. Converter loss will caused for reduced efficiency of the system. By introducing soft switched converters and loss compensation for filter inductance loss we can improve the overall efficiency of grid inter phase PV system.

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